Counting good truth assignments of random k-SAT formulae

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Abstract

We present a deterministic approximation algorithm to compute *logarithm* of the number of 'good' truth assignments for a random k-satisfiability (k-SAT) formula in polynomial time (by 'good' we mean that violates a small fraction of clauses). The relative error is bounded above by an arbitrarily small constant ϵ with high probability[1] as long as the clause density (ratio of clauses to variables) $\alpha < \alpha_{\mathrm{u}}(k) = 2k^{-1} \log k(1+o(1))$. The algorithm is based on computation of marginal distribution via belief propagation and use of an interpolation procedure. This scheme substitutes the traditional one based on approximation of marginal probabilities via MCMC, in conjunction with self-reduction, which is not easy to extend to the present problem.

Our results are expected hold for a reasonable non-random setup with locally tree-like sparse k-SAT formulas. We derive $2k^{-1} \log k(1+o(1))$ as threshold for uniqueness of the Gibbs distribution on satisfying assignment of random infinite tree k-SAT formulae to establish our results, which is of interest in its own right.

1 Introduction

1.1 Setup and Problem Statement. Given N boolean variables $x_i, 1 \leq i \leq N$, an M clause k-satisfiability (k-SAT) formula has the form $F = \wedge_{j=1}^{M} C_j$, where $C_j = \vee_{\ell=1}^{k} z_{j\ell}$ with literal $z_{j\ell}$ being either x_i for $\bar{x}_i$ for some $1 \leq i \leq N$. An assignment $\underline{x} \in \{0,1\}^N$ of variables $x_i, 1 \leq i \leq N$ satisfies clauses C_j if at least of one the k literals of C_j evaluates to be true. We will denote true by "1" and false by "0". For given F, $E(\underline{x})$ denote the number of unsatisfied clauses of F under assignment $\underline{x}$. Given $\beta \in \mathbb{R}_+$ (called *inverse temperature* in statistical physics), define *partition function* as

$$Z_N(\beta, F) \equiv \sum_{\underline{x} \in \{0,1\}^N} e^{-\beta E(\underline{x})}. \qquad (1.1)$$

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[1]In this paper, by term "with high probability" (whp) we mean with probability $1 - o_N(1)$.

Notice that $Z_N(\beta, F)$ weighs in favor of "good" assignments, i.e. assignments that satisfy more clauses. As $\beta \to \infty$, $Z_N(\beta, F)$ becomes the number of assignments that satisfy (all clauses of) F. The partition function naturally arises as normalizing constant in the following probability measure on $\{0,1\}^N$, often denoted as *Gibbs* distribution (also known as *Boltzmann* distribution) [1] related to F: for $\underline{x} \in \{0,1\}^N$,

$$\mu_{\beta,F}(\underline{x}) = \frac{1}{Z_N(\beta, F)} \prod_{j=1}^{M} \psi_j(\underline{x}) = \frac{e^{-\beta E(\underline{x})}}{Z_N(\beta, F)}, \quad (1.2)$$

where $\psi_j(\underline{x}) = \begin{cases} 1 & \text{if } \underline{x} \text{ satisfy clause } C_j, \\ e^{-\beta} & \text{otherwise.} \end{cases}$

We shall write $\mu(\cdot) = \mu_{\beta,F}(\cdot)$ whenever it will not be necessary to specify the formula and inverse temperature. We further denote by $\langle \cdot \rangle = \langle \cdot \rangle_{\beta,F}$ expectations with respect to the measure μ.

In this paper, we are interested in *random k-SAT* formulas. These are generated by selecting M clauses independently and uniformly at random from all possible $2^k \binom{N}{k}$ k-clauses. Specifically, we let M scale linearly in N, i.e. $M = \alpha N$ for $\alpha \in \mathbb{R}_+$.

The main motivation in this paper is to describe an efficient algorithm to compute a good approximation of $Z_N(\beta, F)$ for such random formulas. An important open problem is to characterize the limit $\lim_{N \to \infty} \frac{1}{N} \log Z_N(\beta, F)$ for generic $\alpha, \beta \in \mathbb{R}_+$, and F distributed according to the random k-SAT model. The analysis of our algorithm implies such a characterization for all finite β, and α smaller than a critical value.

1.2 Related Previous Work. The well-known threshold conjecture for random k-SAT states that for all $k \geq 2$, there exists $\alpha_{\mathrm{c}}(k)$ such that for $\alpha < \alpha_{\mathrm{c}}(k)$ (resp. $\alpha > \alpha_{\mathrm{c}}(k)$) the randomly generated formula is satisfiable (resp. not satisfiable) with probability 1 as $N \to \infty$. There has been a lot of interesting work on this topic, and a convergence of methods from different communities [2, 3, 4]. Due to space limitation, we will recall only some of the key relevant results.

Friedgut [14] established existence of a sharp threshold. More precisely, he proved that there exists $\alpha_{\mathrm{c}}(k, N)$ such that for any $\varepsilon > 0$ the satisfiability probability tends to 1 (to 0) if $\alpha < \alpha_{\mathrm{c}}(k, N)(1 - \varepsilon)$ (respectively

$\alpha > \alpha_c(k,N)(1 + \varepsilon))$ as $N \to \infty$. While it is expected that $\lim_{N\to\infty} \alpha_c(k,N)$ exists, it has remained elusive so far. Recently, Achlioptas and Peres [6] established that $\alpha_c(k,N) = 2^k \log 2(1 + o_k(1))$ thus implying that $\alpha_c(k,N)$ converges up to an order independent of N.

In particular the existence of $\lim_{N\to\infty}\lim_{\beta\to\infty}\frac{1}{N}\log Z_N(\beta,F)$ with probability 1, for all $\alpha \in \mathbb{R}_+$ and $k \geq 2$ would establish the threshold conjecture. More generally, the log-partition function at $\beta = \infty$ provides detailed information about the satisfying assignments (computing it exactly is #-P complete in the worst case). In [7] a formula for the limit log-partition function was derived through the non-rigorous replica method from statistical physics. The existence of the $N \to \infty$ limit was proved by Franz, Leone and Toninelli [8, 9] for even k and all values of α. These authors also provided an upper bound on $\lim_{N\to\infty}\frac{1}{N}\log Z_N(\beta,F)$. However evaluating the bound requires solving an *a priori* complex optimization problem, and a matching lower bound wasn't proved there. Talagrand [5] established the existence of the limit and its value for very small value of β (depending on k).

1.3 Overview of Results. In this paper, we essentially prove that the Gibbs distribution (1.2) is a *pure state* (equivalently unique) [1] by establishing appropriate worst-case *correlation decay* for tree formulae. The approach of Talagrand [5] also crucially relied of proving correlation decay, albeit with different means. This resulted in a limitation to small values of β and thus leaving out the interesting regime of large β.

An analogy can be drawn with the Markov Chain Monte Carlo (MCMC) approach to the approximate computation of partition functions (see, for example, work by Jerrum and Sinclair [10]). In that case, the crucial step consists in proving fast mixing condition ('temporal' correlation decay) for some Markov Chain. The same role is played here by 'spatial' correlation decay with respect to the measure (1.2).

In this paper, we establish correlation decay for random k-SAT formula for a range of α and all β. This allows us to estabilish that deterministic Belief Propagation (BP) algorithm provides a good approximation of the marginals with respect to the distribution (1.2), cf. Section 3. In the usual MCMC approach, marginals are used to approximate the partition function by recursively fixing the variables and exploiting self-reducibility. Usually, fast mixing property is established under worst-case situation and hence estimating marginal probabilities in reduced problem is fast as well. In our setup, we establish correlation decay (analogous to fast mixing in MCMC) for randomly chosen formula. In case of random k-SAT, the formula after self-reduction does not preserve distri-

butional properties. Hence, even though we can use BP in estimating marginal distributions we can use trick of self-reducibility to iteratively compute marginal distributions. To overcome this challenge, we use *interpolation* in β, to obtain $\log Z_N(\beta,F)$ approximately (Theorem 1). The analysis of the approximation scheme implies the existence of the limit $\lim_{N\to\infty}\frac{1}{N}\log Z_N(\beta,F)$ (Theorem 3). Finally, we show that the computation of the partition function leads to an estimate of the number of truth assignments that violate at most $N\varepsilon$ clauses, for small ε (Theorem 4). As a byproduct, we obtain an asymptotically (in k) threshold for uniqueness Gibbs measure on infinite k-SAT tree formula (Theorem 2).

We note that the approach taken in this paper for counting weighted assignment applies to other discrete problems as long as the following conditions are met: (*i*) The underlying graph structure is sparse (i.e. most of the vertices have a tree neighborhood). (*ii*) Let $\psi(\underline{x})$ be the weight of assignment $\underline{x}$; then one should consider the problem with weight $\psi(\underline{x})^\gamma$ for $\gamma \in [0,1]$. In particular, for $\gamma = 0$ by definition one must have $\psi(\underline{x})^\gamma = 1$ for any $\underline{x}$, and $\log \psi(\underline{x})$ must be bounded by a polynomial in N. (*iii*) The worst case correlation decay condition must hold for Gibbs distribution with weights proportional to $\psi(\underline{x})^\gamma$ for any $\gamma \in [0,1]$.

We hope that this approach for counting will find applications in other hard combinatorial problems. Similar schemes were recently discussed by Weitz [11], Bandyopadhyay and Gamarnik [12] for counting independent sets approximately via deterministic algorithms.

1.4 Organization. Section 2 presents preliminaries and statements of the main results. Section 3 describes the approximate counting algorithm and the proof of key Lemmas related to the correlation decay (or uniqueness) of Gibbs distribution on random *tree* k-SAT. Section 4 completes the proofs of all main results stated in Section 2. We present direction for future work in Section 5.

2 Preliminaries and Main Results

Given α and k, define $\alpha_*(k)$ to be the smallest positive root of the equation $\kappa(\alpha) = 1$, where

$$\kappa(\alpha) \equiv k(k-1)\alpha\left(1 - \frac{1}{4}e^{-k\alpha/2}\right)\left(1 - \frac{1}{2}e^{-k\alpha/2}\right)^{k-2}. \quad (2.3)$$

For $k = 2, 3, 4, 6$, the $\alpha_*(k)$ is approximately $0.58216, 0.293, 0.217, 0.16670$. Asymptotically, $\alpha_*(k) = 2k^{-1}\log k\left(1 + O\left(\frac{\log\log k}{\log k}\right)\right)$. Now, we state the main result of this paper about approximating logarithm of partition function.

THEOREM 1. *Given $\varepsilon > 0$, $\alpha < \alpha_*(k)$ and $N(\varepsilon)$ (large enough) so that for any $N \geq N(\varepsilon)$ there exists $\delta > 0$ and*

a polynomial (in N, independent of ε) time algorithm that computes a number $\Phi(\beta, F)$ for $\beta \in \mathbb{R}$ and a satisfiability formula F so that following holds: if $\beta \in [0, N^\delta]$ and F is a random k-SAT formula with N variables, $M = N\alpha$ clauses, then with high probability

$$\Phi(\beta, F)(1 - \varepsilon) \leq \log Z_N(\beta, F) \leq \Phi(\beta, F)(1 + \varepsilon). \quad (2.4)$$

The proof of Theorem 1 requires us to prove uniqueness of Gibbs measure for the model (1.2) on infinite tree random k-SAT formulae. To state this result, we first need some definitions. An appropriate model for tree random k-SAT, $\mathsf{T}_*(r)$ is described as follows: For $r = 0$, it is the graph containing a unique variable node. For any $r \geq 1$, start by a single variable node (the root) and add $l \overset{\mathrm{d}}{=} \mathsf{Poisson}(k\alpha)$ clauses, each one including the root, and $k - 1$ new variables (first generation variables). For each one of the l clauses, the corresponding literals are non-negated or negated independently with equal probability. If $r \geq 2$, generate an independent copy of $\mathsf{T}_*(r - 1)$ for each variable node in the first generation and attach it to them. By construction, for any $r' < r$ the first r' generations of a tree from $\mathsf{T}_*(r)$ are distributed according to the model $\mathsf{T}_*(r')$. As a consequence, the infinite tree distribution $\mathsf{T}_*(\infty)$ is also well defined. In what follows, we denote the root of $\mathsf{T}_*(\cdot)$ as 0. Let μ denote the Gibbs distribution on random formula on $\mathsf{T}_*(r)$ (cf. (1.2)) and $\mu_{0|r}(x_0 | \underline{x}_r)$ be the conditional distribution of root variable conditional to the assignment of r-th generation nodes of $\mathsf{T}_*(r)$ according to $\underline{x}_r$. The key property for most of the results of this paper is that of correlation decay with respect to random tree formulas $\mathsf{T}_*(\cdot)$.

DEFINITION 1. *Given $\alpha, \beta \in \mathbb{R}_+$ and $k \geq 2$, the Gibbs distribution defined by (1.2) on the random tree $\mathsf{T}_*(\cdot)$ is unique with exponential correlation decay if there exists positive constants $A, \gamma > 0$, such that*

$$\mathbb{E}\left[\sup_{\underline{x}_r, \underline{z}_r} \left\| \mu_{0|r}(\cdot | \underline{x}_r) - \mu_{0|r}(\cdot | \underline{z}_r) \right\|_{\mathrm{TV}}\right] \leq A\, e^{-\gamma r}, \quad (2.5)$$

for any $r \geq 0$ (here, expectation is w.r.t. distribution on trees). The uniqueness threshold $\alpha_{\mathrm{u}}(k)$ is the supremum value of α such that the above condition is verified for any $\beta \in [0, \infty]$.

The property defined here is stronger than the usual notion of correlation decay, which only requires $\left\| \mu_{0|r}(\cdot | \underline{x}_r) - \mu_{0|r}(\cdot | \underline{z}_r) \right\|_{\mathrm{TV}} \to 0$ as $r \to \infty$ almost surely. Let $\alpha_{\mathrm{u}}'(k)$ denote the threshold for this weaker property. To the best of our knowledge, nothing has been known about the precise values of $\alpha_{\mathrm{u}}(k), \alpha_{\mathrm{u}}'(k)$ or the relation between them other than trivial lower bound from percolation threshold of $\Omega(k^{-2})$. We establish the precise asymptotic behavior of $\alpha_{\mathrm{u}}(k)$ and show that $\alpha_{\mathrm{u}}(k) = \alpha_{\mathrm{u}}'(k)(1 + o_k(1))$ as stated below.

THEOREM 2. *For the Gibbs distribution (1.2) defined on $\mathsf{T}_*(\cdot)$ as above,*

$$\alpha_{\mathrm{u}}(k) = \frac{2\log k}{k}\left\{1 + O\left(\frac{\log\log k}{\log k}\right)\right\},$$

$$\alpha_{\mathrm{u}}'(k) = \frac{2\log k}{k}\left\{1 + O\left(\frac{\log\log k}{\log k}\right)\right\}. \quad (2.6)$$

Though algorithmically we obtain approximation of $\log Z_N(\beta, F)$, it is possible to establish the convergence of $\frac{1}{N}\log Z_N(\beta, F)$ with probability 1. Before stating this result, we need some definitions. In what follows, define function $f : \mathbb{R}^{k-1} \to \mathbb{R}$ as

$$f(x_1, \ldots, x_{k-1})$$
$$= -\frac{1}{2}\log\left\{1 - \frac{1 - e^{-\beta}}{2^{k-1}}\prod_{i=1}^{k-1}(1 - \tanh x_i)\right\}. \quad (2.7)$$

Let $\mathcal{D}$ denote the space of probability distributions on the real line $\mathbb{R}$. Define $S, S_1, S_2 : \mathcal{D} \to \mathcal{D}$ as follows: Given $\mu \in \mathcal{D}$, define random variable $u = f(h_1, \ldots, h_{k-1})$ where $h_1, \ldots, h_{k-1}$ are i.i.d. with distribution μ. Define distribution of u as $S_1(\mu)$. Given a distribution $\nu \in \mathcal{D}$, let random variable $h_0 = \sum_{a=1}^{\ell^+} u_a - \sum_{b=1}^{\ell^-} u_b$, where ℓ^+, ℓ^- are independent Poisson random variables with mean $k\alpha/2$ and u_a, u_b are i.i.d. with distribution ν. Let distribution of h_0 be denoted by $S_2(\nu)$. Define $S \equiv S_1 \circ S_2$. Now, we state the result.

THEOREM 3. *Given k, let $\alpha < \alpha_*(k)$ and $\beta \in [0, \infty)$. Then, the function $S : \mathcal{D} \to \mathcal{D}$ as defined above has unique fixed point, say μ^*. Let $\nu^* = S_2(\mu^*)$. Then,*

$$\frac{1}{N}\log Z(\beta, F_N) \overset{\mathrm{a.s.}}{\to} \phi(\beta), \quad (2.8)$$

where

$$\phi(\beta) = -k\alpha\mathbb{E}\log[1 + \tanh h \tanh u]$$

$$+ \alpha\mathbb{E}\log\left\{1 - \frac{1}{2^k}(1 - e^{-\beta})\prod_{i=1}^{k}(1 - \tanh h_i)\right\}$$

$$+ \mathbb{E}\log\left\{\prod_{i=1}^{\ell_+}(1 + \tanh u_i^+)\prod_{i=1}^{\ell_-}(1 - \tanh u_i^-)\right.$$

$$\left. + \prod_{i=1}^{\ell_+}(1 - \tanh u_i^+)\prod_{i=1}^{\ell_-}(1 + \tanh u_i^-)\right\} \quad (2.9)$$

where $u, u_i^\pm$ are i.i.d. with distribution μ^*, h, h_j are i.i.d. with distribution ν^* and $\ell_\pm$ are Poisson of mean $k\alpha/2$.

Finally, define $\Xi(\zeta, F)$ to be the number of assigments that violate at most ζ clauses. The next result formalizes the relation between the approximation of $Z_N(\beta, F)$ and counting the number of truth assignments that violate a small fraction of clauses.

THEOREM 4. *For any $k \geq 2$, $\varepsilon > 0$, and $\alpha < \alpha_*(k)$ there exists $A, C > 0$, $a > 0$ such that the following is true. If F is a random k-SAT with $M = N\alpha$ clauses over N variables, and $\beta = A \log \varepsilon^{-1}$, then*

$$|\log \Xi(N\varepsilon, F) - \Phi(\beta, F)| \leq NC\varepsilon^a, \qquad (2.10)$$

with high probability, where $\Phi(\beta, F)$ is defined in Theorem 1.

3 Algorithm and Key Lemmas

3.1 Algorithm. We first define a factor graph G_F for a given formula F: each variable is represented by (circle) variable node and each clause by a (square) clause node with an edge between a variable and a clause node only if corresponding variable belongs to the clause. The edge is solid if variable is non-negated and dashed if variable is negated. The Belief Propagation (BP) algorithm is a heuristic (exact for tree factor graphs) to estimate the marginal distribution of node variables for any factor graph. Specifically, we will use BP to approximately compute marginals of the distribution (1.2).

We will quickly recall BP for our specific setup. We refer reader to see [15, 16] for further details on the algorithm. BP is a message passing algorithm in which at each iteration messages are sent from variable nodes to neighboring clause nodes and vice versa. The messages at iteration $t + 1$ are functions of messages received at iteration t. To describe the message update equations, we need some notation. Let ∂a denote the set of all variables that belong to clause a. If variable x_i is involved in clause a as literal z (either $z = x_i$ or $z = \bar{x}_i$), then define $\partial_+ i(a)$ as the set of all clauses (minus a) in which x_i appears as z. Similarly, $\partial_- i(a)$ denotes the set of all clauses in which x_i appears as $\bar{z}$. Let $\{h_{i \to a}^{(t)}\}$, $\{u_{a \to i}^{(t)}\}$ denote the messages (precisely, they are half log-likelihood ratios) that are passed along the directed edges $i \to a$ and $a \to i$ respectively at time t, then the update equations are

$$h_{i \to a}^{(t+1)} = \sum_{b \in \partial_+ i(a)} u_{b \to i}^{(t)} - \sum_{b \in \partial_- i(a)} u_{b \to i}^{(t)},$$

$$u_{a \to i}^{(t)} = f(\{h_{j \to a}^{(t)}; j \in \partial a \setminus i\}), \qquad (3.11)$$

where the function $f(\cdot)$ has been defined in Eq. (2.7). We shall assume [2] that the update equations are initialized by $h_{i \to a}^{(0)} = 0$ and algorithm stops at iteration $t_{\max}$ which is equal to the diameter of G_F. Let $(h_{i \to a}, u_{a \to i})$ be messages passed in the last iteration of BP. Using these messages, an estimate of the probability that a clause is satisfied can be obtained as follows. Let $E_a(\underline{x}_{\partial a})$ be the indicator function for the a-th clause not being satisfied.

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[2]In fact an arbitrary initial condition and a smaller number of iterations wouldn't change our main results.

As mentioned above, $h_{i \to a}$ is thought of as half log-likelihood ratio for i satisfying a and i not satisfying a, in the absence of clause a itself. A little algebra then shows that the BP estimate for the expectation of $E_a(\underline{x}_{\partial a})$ is

$$\langle E_a(\underline{x}_{\partial a})\rangle_{\mathrm{BP}} = \frac{\sum_{\underline{x}_{\partial a}} E_a(\underline{x}_{\partial a}) \exp\{-\beta E_a(\underline{x}_{\partial a}) + h_{i \to a}\sigma_{ai}(x_i)\}}{\sum_{\underline{x}_{\partial a}} \exp\{-\beta E_a(\underline{x}_{\partial a}) + h_{i \to a}\sigma_{ai}(x_i)\}},$$

where $\sigma_{ai}(x) = +1$ if setting $x_i = x$ satisfies clause a, and $= -1$ otherwise. We further introduce the number of clauses violated by $\underline{x}$, $E(\underline{x}) = \sum_a E_a(\underline{x}_{\partial a})$, and its BP estimate $\langle E(\underline{x})\rangle_{\mathrm{BP}} = \sum_a \langle E_a(\underline{x})\rangle_{\mathrm{BP}}$.

Given $\beta > 0$, we let $\beta_i = i\beta/N^2$, for $i = 0, \ldots, n \equiv N^2$. Then,

$$\begin{aligned}
\log Z(\beta, F) &= \log Z(0, F) + \sum_{i=0}^{n-1} \log \frac{Z(\beta_{i+1}, F)}{Z(\beta_i, F)} \\
&= N \log 2 + \sum_{i=0}^{n-1} \log\langle e^{-\Delta E(\underline{x})}\rangle_i, \quad (3.12)
\end{aligned}$$

where $\Delta \equiv \beta_{i+1} - \beta_i$, and $\langle \cdot \rangle_i$ is a shorthand for expectation with respect to the measure $\mu_{\beta_i, F}(\cdot)$. The above expression is difficult to evaluate. However, due to Δ being small, $\langle -\Delta E(\underline{x})\rangle$ is a good estimate of $\log\langle e^{-\Delta E(\underline{x})}\rangle_i$. Hence, define the algorithm estimate as

$$\Phi(\beta, F) = N \log 2 - \sum_{i=1}^{n-1} \Delta \langle E(\underline{x})\rangle_{\mathrm{BP},i}, \qquad (3.13)$$

where the subscript in $\langle \cdot \rangle_{\mathrm{BP},i}$ emphasizes that the BP computation must be performed at inverse temperature β_i.

3.2 Key Lemmas. Before presenting a few useful Lemmas, let us mention a few facts. Given factor graph G_F and variable node i, $1 \leq i \leq N$, let $\mathsf{B}_i(r)$ denote subgraph induced by the set of all variable that are within shortest path distance r of node i (the distance between two variables sharing a clause being set to 1). Analogously, for a clause node a, $\mathsf{B}_a(r)$ is the union of $\mathsf{B}_i(r)$ with i running over the variables involved in a. Let A be subset of variable nodes. Then, let $\underline{x}_A$ denote an assignment to the corresponding variables. Given two such subsets $A, B \subseteq [N]$ and assignments $\underline{x}_A$, $\underline{x}_B$, let $\mu_{A|B}(\underline{x}_A|\underline{x}_B)$ be the conditional probability under the distribution (1.2) of the variables in A, given assignment $\underline{x}_B$ on B. The following is a well-known result about BP algorithm (see [17]).

LEMMA 3.1. *Given a clause a in a k-SAT formula and an integer $r \geq 0$, assume $\mathsf{B}_a(r + 1)$ to be a tree. Let*
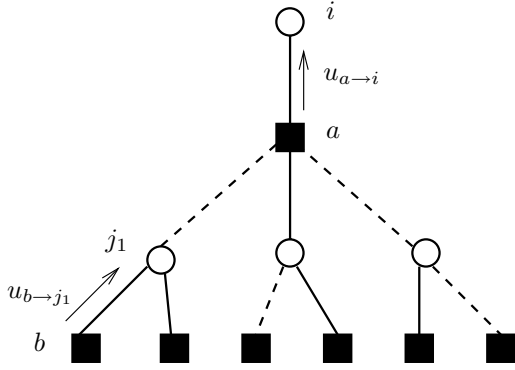
Figure 1: Pictorial representation of the recursion (3.19) on the factor graph G_F: filled squares represent function nodes and empty circles variable nodes. Dashed edges correspond to negations.

$U = \mathsf{B}_a(r)$ and $V = [N]\backslash U$. Then

$$|\langle E_a(\underline{x}_{\partial a})\rangle - \langle E_a(\underline{x}_{\partial a})\rangle_{\mathrm{BP}}| \le \sup_{\underline{y},\underline{z}} \left\| \mu_{\partial a|V}(\cdot|\underline{y}_V) - \mu_{\partial a|V}(\cdot|\underline{z}_V) \right\|_{\mathrm{TV}},$$

$$0 \le \langle E_a(\underline{x}_{\partial a})\rangle, \langle E_a(\underline{x}_{\partial a})\rangle_{\mathrm{BP}} \le \max_{\underline{z}_V}\left\{ \sum_{\underline{x}_{\partial a}} E_a(\underline{x})\mu_{\partial a|V}(\underline{x}_{\partial a}|\underline{z}_V)\right\}$$

$$(3.14)$$

Next, we present a known result about locally tree-like structure of random k-SAT formula (an analogous result concerns the local structure of sparse random graphs).

LEMMA 3.2. *Consider* $k \ge 2$, $\alpha \in [0,\infty)$ *and a random k-SAT formula F with clause density α. For $r \ge 0$, let $\mathsf{B}_i(r)$ be the ball of radius r centered at a uniformly random variable node i. Let $S(r)$ be an r-generation tree distributed as $\mathsf{T}_*(r)$ (with the same values of k and α). Then, there exists A, ρ (dependent on α, k) such that*

$$\| \mathbb{P}\{\mathsf{B}_i(r) \in \cdot\} - \mathbb{P}\{S(r) \in \cdot\} \|_{\mathrm{TV}} \le \frac{A\,e^{\rho r}}{N}. \quad (3.15)$$

LEMMA 3.3. *Let $\alpha_*(k)$ be the smallest positive root of the equation $\kappa(\alpha) = 1$, with $\kappa(\alpha)$ defined as in Eq. (2.3). Then $\alpha_*(k) \le \alpha_{\mathrm{u}}(k)$.*

Proof: Given an r-generations tree formula F, consider an edge $i \to a$ directed toward the root and the subtree rooted at i and *not* containing a. Denote by $\mu_{i \to a}(\cdot)$ the marginal distribution of x_i with respect to the model associated to this subtree, and let $h_{i \to a} \in [-\infty, \infty]$ be the corresponding log-likelihood ratio

$$h_{i \to a} \equiv \frac{1}{2} \log\left\{ \frac{\mu_{i \to a}(x_i \text{ satisfies } a)}{\mu_{i \to a}(x_i \text{ doesn't satisfy } a)}\right\}. \quad (3.16)$$

Analogously, given an edge $a \to i$, we consider the subtree rooted at i and containing only a among the clauses involving i. We denote by $\mu_{a \to i}(\cdot)$ the corresponding marginal distribution at i, and let

$$u_{a \to i} \equiv \frac{1}{2} \log\left\{ \frac{\mu_{a \to i}(x_i \text{ satisfies } a)}{\mu_{a \to i}(x_i \text{ doesn't satisfy } a)}\right\}. \quad (3.17)$$

It is easy to show that these log-likelihoods satisfy the recursions[3]

$$\begin{aligned} h_{j \to a} &= \sum_{b \in \partial_+ j(a)} u_{b \to j} - \sum_{b \in \partial_- j(a)} u_{b \to j}, \\ u_{a \to i} &= f(\{h_{j \to a}; j \in \partial a \backslash i\}), \end{aligned} \quad (3.18)$$

with the function $f(\cdot)$ being defined as in Eq. (2.7). For the calculations below, it is convenient to eliminate the $h_{i \to a}$ variables, to get

$$u_{a \to i} = f\left(\sum_{b \in \partial_+ j_1(a)} u_{b \to j_1} - \sum_{b \in \partial_- j_1(a)} u_{b \to j_1}; \right. \quad (3.19)$$

$$\left. \ldots; \sum_{b \in \partial_+ j_{k-1}(a)} u_{b \to j_{k-1}} - \sum_{b \in \partial_- j_{k-1}(a)} u_{b \to j_{k-1}} \right),$$

where we denoted by $j_1, \ldots, j_{k-1}$ the indices of variables involved in clause a (other than i). A pictorial representation of this recursion is provided in Fig. 1.

Notice that the above recursions hold irrespective whether one considers the unconditional measure $\mu(\cdot)$, or the conditional one $\mu(\cdot|\underline{x}_r)$. What changes in the two cases are the initial condition for the recursion, i.e. the value of $h_{i \to a}$ associated with the variables i at the r-th generation. For the unconditioned measure ('free boudary condition'), the appropriate initialization is $h_{i \to a} = 0$. If one conditions to $\underline{x}_r$, $h_{i \to a} = +\infty$, or $= -\infty$ depending (respectively) whether x_i satisfy clause a or not.

In rest of the proof, we consider the conditioned measure $\mu(\cdot|\underline{x}_r)$. As a consequence, the log-likelihoods are, implicity, functions of $\underline{x}_r$: $u_{a \to i} = u_{a \to i}(\underline{x}_r)$ (indeed of the restriction of $\underline{x}_r$ to the subtree rooted at i, and only containing a). We then let

$$\overline{u}_{a \to i} = \max_{\underline{x}_r}\ u_{a \to i}(\underline{x}_r), \qquad \underline{u}_{a \to i} = \min_{\underline{x}_r}\ u_{a \to i}(\underline{x}_r). \quad (3.20)$$

In the case $\beta = \infty$, the maximum (minimum) is taken over all boundary conditions $\underline{x}_r$, such that the subformula rooted at i admits at least one solutions, under the condition $\underline{x}_r$ (there is always at least one such boundaries). We further let $\Delta_{a \to i} = \overline{u}_{a \to i} - \underline{u}_{a \to i} \ge 0$.

---

[3] The reader will notice that these coincide with the BP update equations, cf. Eq. (3.11), which are known to be exact on trees.

Consider a random tree distributed as $\mathsf{T}_*(r)$, conditioned to the root having degree 1, i.e. to the root variable being involved in a unique clause, to be denoted by a. Let $\Delta^{(r)} = \Delta_{a\to i}$ be the corresponding log-likelihoods interval.

Claim 1. $\mathbb{E}\tanh\Delta^{(r)} \le e^{-\gamma r}$ for some $\gamma > 0$.

The above claim is proved later. We first use it to establish Lemma 3.3. Let $\partial_+ 0$ be the set of clauses in which the root is involved as the direct literal, $\partial_- 0$ be the set in which it is involved as negated. Then

$$\left|\left|\mu_{0|r}(\,\cdot\,|\underline{x}_r) - \mu_{0|r}(\,\cdot\,|\underline{z}_r)\right|\right|_{\mathrm{TV}} = \frac{1}{2}\left|\tanh h_0(\underline{x}_r) - \tanh h_0(\underline{z}_r)\right|$$

$$h_0(\underline{x}_r) \equiv \sum_{a\in\partial_+ 0} u_{a\to 0}(\underline{x}_r) - \sum_{a\in\partial_- 0} u_{a\to 0}(\underline{x}_r)\,.$$

Since $x \mapsto \tanh(x)$ is monotonically increasing in x, we have

$$\left|\left|\mu_{0|r}(\,\cdot\,|\underline{x}_r) - \mu_{0|r}(\,\cdot\,|\underline{z}_r)\right|\right|_{\mathrm{TV}} \le \frac{1}{2}\left\{\tanh\overline{h}_0 - \tanh\underline{h}_0\right\};$$

$$\overline{h}_0 \equiv \sum_{a\in\partial_+ 0} \overline{u}_{a\to 0} - \sum_{a\in\partial_- 0} \underline{u}_{a\to 0}\,,$$

$$\underline{h}_0 \equiv \sum_{a\in\partial_+ 0} \underline{u}_{a\to 0} - \sum_{a\in\partial_- 0} \overline{u}_{a\to 0}\,. \qquad (3.21)$$

Using the elementary properties $\tanh x - \tanh y \le 2\tanh(x-y)$ for any $x \ge y$, and $\tanh(x+y) \le \tanh x + \tanh y$ for $x, y \ge 0$, we get

$$\left|\left|\mu_{0|r}(\,\cdot\,|\underline{x}_r) - \mu_{0|r}(\,\cdot\,|\underline{z}_r)\right|\right|_{\mathrm{TV}} \le \tanh\left\{\sum_{a\in\partial 0}\Delta_{a\to 0}\right\}$$

$$\le \sum_{a\in\partial 0}\tanh\Delta_{a\to 0}\,.$$

We can take the maximum over boundary condition and the expectation with respect to the tree ensemble. Recalling that $|\partial 0|$ is a Poisson random variable of mean $k\alpha$, we get

$$\mathbb{E}\max_{\underline{x},\underline{z}}\left|\left|\mu_{0|r}(\,\cdot\,|\underline{x}_r) - \mu_{0|r}(\,\cdot\,|\underline{z}_r)\right|\right|_{\mathrm{TV}} \le k\alpha\,\mathbb{E}\tanh\Delta^{(r)}\,,$$

which implies the Lemma 3.3 with $A = k\alpha$ thus completing its proof. $\qquad\square$

Proof of Claim 1. Now we prove $\mathbb{E}\tanh\Delta^{(r)} \le e^{-\gamma r}$. It is easy to realize that $f(x_1,\dots,x_{k-1})$ is monotonically decreasing in each of its arguments. Therefore Eq. (3.19) yields the following recursion for upper/lower bounds

$$\overline{u}_{a\to i} = f\left(\sum_{b\in\partial_+ j_1(a)}\underline{u}_{b\to j_1} - \sum_{b\in\partial_- j_1(a)}\overline{u}_{b\to j_1};\ \dots\ ;\right.$$

$$\left.\sum_{b\in\partial_+ j_{k-1}(a)}\underline{u}_{b\to j_{k-1}} - \sum_{b\in\partial_- j_{k-1}(a)}\overline{u}_{b\to j_{k-1}}\right),$$

together with the equation obtained by interchanging $\underline{u}_{\dots}$ and $\overline{u}_{\dots}$. By taking the difference of these two equations, we get

$$\Delta_{a\to i} = f(\underline{h}_1;\ \dots\ ;\underline{h}_{k-1}) - f(\overline{h}_1;\ \dots\ ;\overline{h}_{k-1})\,,\quad(3.22)$$

where $\underline{h}_i = \sum_{b\in\partial_+ j_i(a)}\underline{u}_{b\to j_i} - \sum_{b\in\partial_- j_i(a)}\overline{u}_{b\to j_i}$ and $\overline{h}_i = \sum_{b\in\partial_+ j_i(a)}\overline{u}_{b\to j_i} - \sum_{b\in\partial_- j_i(a)}\underline{u}_{b\to j_i}$ (obviously $\underline{h}_i \ge \overline{h}_i$).

Suppose now that n out of the $k-1$ variables $x_{j_1},\dots,x_{j_{k-1}}$ are pure literals, let's say variables $x_{j_1},\dots,x_{j_n}$. This means that $\partial_- j_1(a),\dots\partial_- j_n(a) = \emptyset$, and therefore, since the loglikelihoods $u_{b\to j}$ are non-negative (because f is non-negative), $\underline{h}_1,\dots\underline{h}_n \ge 0$. It is an easy exercise of analysis to show that, if $x_1,\dots,x_n \ge 0$,

$$0 \le -\frac{\partial f}{\partial x_i}(x_1,\dots,x_{k-1}) \le \frac{1}{2^n}\,. \qquad (3.23)$$

This is proved by computing explicitly $-\frac{\partial f}{\partial x_i}$ and noticing that it is decreasing in each of its arguments. Therefore, by the Mean Value Theorem

$$\Delta_{a\to i} \le \frac{1}{2^n}\sum_{l=1}^{k-1}(\overline{h}_l - \underline{h}_l) = \frac{1}{2^n}\sum_{l=1}^{k-1}\sum_{b\in\partial j_l}\Delta_{b\to j_l}\,,\quad(3.24)$$

Next we take the hyperbolic tangent of both sides, and use again $\tanh(x+y) \le \tanh x + \tanh y$, for $x, y \ge 0$ to get

$$\tanh\Delta_{a\to i} \le \frac{1}{2^n}\sum_{l=1}^{k-1}\sum_{b\in\partial j_l}\tanh\Delta_{b\to j_l}\,. \qquad (3.25)$$

Finally we take expectation of this inequality. In order to do this, we recall that n is the number of pure literals among $x_{j_1},\dots x_{j_{k-1}}$. In our notations this can be written as $n = \sum_{l=1}^{k-1}\mathbb{I}(|\partial_- j_l(a)| = 0)$. We further assume that i is the root of a tree from $\mathsf{T}_*(r+1)$, $r \ge 0$ and therefore $\Delta_{a\to i}$ is distributed as $\Delta^{(r+1)}$. Furthermore the differences $\Delta_{b\to j_l}$ will be distributed as $\Delta^{(r)}$. We thus obtain

$$\mathbb{E}\tanh\Delta^{(r+1)} \le \mathbb{E}\left\{\prod_{l=1}^{k-1}\frac{1}{2^{\mathbb{I}(|\partial_- j_l(a)|=0)}}\sum_{l=1}^{k-1}\sum_{b\in\partial j_l(a)}\tanh\Delta^{(r)}\right\}$$

$$= (k-1)\,\mathbb{E}\left\{\frac{1}{2^{\mathbb{I}(|\partial_- j|=0)}}|\partial j|\right\}\left\{\mathbb{E}\,2^{-\mathbb{I}(|\partial_- j|=0)}\right\}^{k-2}\mathbb{E}\tanh\Delta^{(r)}.$$

The expectations over $|\partial_+ j|$, $|\partial_- j|$ are easily evaluated by recalling that these are inependent Poisson random variables of mean $k\alpha/2$. One finally obtains $\mathbb{E}\tanh\Delta^{(r+1)} \le \kappa(\alpha)\mathbb{E}\tanh\Delta^{(r)}$. The thesis follows (with $\gamma = -\log\kappa(\alpha)$) by noticing that $\mathbb{E}\tanh\Delta^{(0)} \le 1$, and recalling that $\kappa(\alpha) < 1$ for $\alpha < \alpha_*(k)$. $\qquad\square$

Next, we consider the probability, under the measure $\mu(\,\cdot\,)$ that one specific clause is not satisfied, namely

$\langle E_a(\underline{x}) \rangle$. In order to bound the error of the BP estimate this quantity, we need to study the error in estimating the joint distribution of k variables entering in clause a. We choose a clause at random and treat all of its k variables as root of k independent rooted random trees (of depth r) as before. This is justified because singling out a clause tilts the original distribution by at most $O(1/N)$.

Let $\underline{x}_r$ be an assigment for the r-th generation variables. We shall denote by $\langle \cdot \rangle^{(r)}$ the expectation with respect to the graphical model (1.2) associated to a formula constructed as follows. First we generate a uniformly random clause over variables $x_1, \ldots, x_k$. Then we sample k independent trees according to $\mathsf{T}_*(r)$ and root them at $x_1, \ldots, x_k$. We let $\langle \cdot \rangle^{(r)}_{\underline{x}_r}$ be the corresponding conditional expectation, given the assignment to the r-th generation.

LEMMA 3.4. *Let $k \geq 2$, $\alpha < \alpha_*(k)$ and $\beta \in [0, \infty]$. Then there exist two positive constants A, γ, such that*

$$\mathbb{E} \max_{\underline{x}_r, \underline{z}_r} \left| \langle E_a(\underline{x}) \rangle^{(r)}_{\underline{x}_r} - \langle E_a(\underline{x}) \rangle^{(r)}_{\underline{z}_r} \right| \leq A\, e^{-\gamma r}\,. \quad (3.26)$$

Proof: Denote by $\underline{x}_{\partial a} = \{x_1, \ldots, x_k\}$ the zeroth generation variables, by $T_1, \ldots, T_k$ the tree factor graphs drawn from $\mathsf{T}_*(r)$ rooted at variable nodes $1, \ldots, k$. Let $\mu_i(x_i | \underline{x}_r)$, $i \in \{1, \ldots, k\}$ be the conditional distribution for variable x_i with respect to the model associated with the tree T_i. We also let $h_i(\underline{x}_r)$ be the associated log-likelihoods (defined analogously to Eq. (3.16)), and $\underline{h}_i = \max_{\underline{x}_r} h_i(\underline{x}_r)$ ($\overline{h}_i = \min_{\underline{x}_r} h_i(\underline{x}_r)$) be their maximum (minimum) values with respect to the boundary condition.

It is not hard to show that $\langle E_a(\underline{x}) \rangle^{(r)}_{\underline{x}_r} = g(h_1(\underline{x}_r), \ldots, h_k(\underline{x}_r))$ where the function $g : \mathbb{R}^k \to \mathbb{R}$ is defined as follows

$$g(x_1, \ldots, x_k) \equiv \frac{e^{-\beta} \prod_{i=1}^k \frac{1}{2}(1 - \tanh x_i)}{1 - (1 - e^{-\beta}) \prod_{i=1}^k \frac{1}{2}(1 - \tanh x_i)} \quad (3.27)$$

Since $g(x_1, \ldots, x_k)$ is monotonically decreasing in each of its arguments, we have

$$\mathbb{E} \max_{\underline{x}_r, \underline{z}_r} \left| \langle E_a(\underline{x}) \rangle^{(r)}_{\underline{x}_r} - \langle E_a(\underline{x}) \rangle^{(r)}_{\underline{z}_r} \right| \quad (3.28)$$
$$\leq \mathbb{E} \left\{ g(\underline{h}_1, \ldots, \underline{h}_k) - g(\overline{h}_1, \ldots, \overline{h}_k) \right\}\,,$$

where the couples $(\underline{h}_1, \overline{h}_1), \ldots, (\underline{h}_k, \overline{h}_k)$ are i.i.d.'s and distributed as $(\underline{h}_0, \overline{h}_0)$ in the proof of Lemma 3.3, cf. Eq. (3.21). In particular, proceeding as in that proof, we deduce that $\mathbb{E} \tanh(\overline{h}_i - \underline{h}_i) \leq A\, e^{-\gamma r}$. We are left with the task of proving that this implies an analogous bound on the right hand side of Eq. (3.28).

To this end, we first consider a single variable function $\tilde{g} : \mathbb{R} \to \mathbb{R}$ with $0 \leq \tilde{g}(x) \leq 1$ and $-1 \leq \tilde{g}'(x) \leq 0$.

Then

$$\begin{aligned}
\mathbb{E}\{\tilde{g}(\underline{h}_1) - \tilde{g}(\overline{h}_1)\} &\leq \mathbb{P}\{\overline{h}_1 - \underline{h}_1 \geq \Delta\} \\
&\quad + \mathbb{E}\{(\overline{h}_1 - \underline{h}_1)\, \mathbb{I}(\overline{h}_1 - \underline{h}_1 < \Delta)\} \\
&\leq \frac{1}{\tanh \Delta} \mathbb{E} \tanh(\overline{h}_1 - \underline{h}_1) \\
&\quad + \frac{\Delta}{\tanh \Delta} \mathbb{E}\{\tanh(\overline{h}_1 - \underline{h}_1)\, \mathbb{I}(\overline{h}_1 - \underline{h}_1 < \Delta)\} \\
&\leq \frac{1 + \Delta}{\tanh \Delta} \mathbb{E} \tanh(\overline{h}_1 - \underline{h}_1)\,.
\end{aligned} \quad (3.29)$$

The proof is completed by writing $\mathbb{E}\{g(\underline{h}_1, \ldots, \underline{h}_k) - g(\overline{h}_1, \ldots, \overline{h}_k)\} = \sum_{i=0}^k \mathbb{E}\{\tilde{g}_i(\underline{h}_i) - \tilde{g}_i(\overline{h}_i)\}$ where $\tilde{g}_i(x) \equiv g(\overline{h}_1 \ldots \overline{h}_{i-1}, x, \underline{h}_{i+1}, \ldots, \underline{h}_k)$ and observing that $-1 \leq \frac{\partial g}{\partial x_i} \leq 0$. $\qquad \square$

Finally, a result that puts together the above observations to derive the net error in BP estimation.

LEMMA 3.5. *Let $k \geq 2$, $\alpha < \alpha_*(k)$ and $\beta \in [0, \infty]$. Then there exists two positive constants C and $\xi < 1$ such that for any N,*

$$\mathbb{E} \left| \langle E(\underline{x}) \rangle - \langle E(\underline{x}) \rangle_{\mathrm{BP}} \right| \leq C N^\xi\,. \quad (3.30)$$

Proof: By linearity of expectation and using Lemma 3.1, we get

$$\mathbb{E} \left| \langle E(\underline{x}) \rangle - \langle E(\underline{x}) \rangle_{\mathrm{BP}} \right| \leq M \mathbb{E} \left| \langle E_a(\underline{x}) \rangle - \langle E_a(\underline{x}) \rangle_{\mathrm{BP}} \right|$$
$$\leq M \mathbb{E} \left\{ \max_{\underline{x}, \underline{z}} \left| \langle E_a(\underline{x}) \rangle^{(r)}_{\underline{x}_r} - \langle E_a(\underline{x}) \rangle^{(r)}_{\underline{z}_r} \right| \right\}\,.$$

We would like to apply Lemma 3.4, but the expectation in the last expression is taken with respect to the formula F drawn from the random k-SAT ensemble, instead of the tree model $\mathsf{T}_*(r)$. However, the quantity in curly brackets depends only of the radius r neighborhood $\mathsf{B}_a(r)$ of vertex a in G_F. Furthermore is non negative and upper bounded by 1. We can therefore apply Lemma 3.2 and 3.4 to upper bound the last expression by (here $\mathbb{E}_\mathsf{T}$ denotes expectation with respect to the tree ensemble):

$$M \left\| \mathbb{P}\{\mathsf{B}_i(r) \in \cdot\} - \mathbb{P}\{S(r) \in \cdot\} \right\|_{\mathrm{TV}}$$
$$+ M \mathbb{E}_\mathsf{T} \left\{ \max_{\underline{x}, \underline{z}} \left| \langle E_a(\underline{x}) \rangle^{(r)}_{\underline{x}_r} - \langle E_a(\underline{x}) \rangle^{(r)}_{\underline{z}_r} \right| \right\}$$
$$\leq A \alpha\, e^{\rho r} + N A' \alpha\, e^{-\gamma r}$$

The proof is completed by setting $r = \frac{1}{\rho + \gamma} \log N$, which yields Eq. (3.30) with $\xi = \frac{\rho}{\gamma + \rho}$. $\qquad \square$

4 Proofs of Theorems

4.1 Proof of Theorem 1. Clearly, the running time of algorithm described in Section 3 is $O(N^4)$ as total

number of BP runs are $O(N^2)$ and each BP run takes $O(N)$ iterations or $O(N^2)$ serial operations. Now, we'll prove Eq. (2.4).

Notice that for $\alpha < \alpha_c(k, N)(1 - \eta)$, $\beta \in [0, \infty]$ there exists a constant $C(\alpha) > 0$ such that $\log Z(\beta, F) \geq C(\alpha)N \log 2$ whp. This follows from the following two facts for appropriate $C(\alpha)$: (1) at least $C(\alpha)N$ variables do not appear in any clause whp and (2) at least one solution is satisfying assignment whp as $\alpha < \alpha_c(k, N)(1 - \eta)$. Thus, there are at least $2^{C(\alpha)N}$ satisfying assignment, whence $Z_N(\beta, F) \geq 2^{C(\alpha)N}$. Using the existing lower bounds on $\alpha_c(k, N)$ (see [6] and references therein), it follows that $\alpha_u(k) \leq \alpha_c(k, N)(1 - \eta)$ for some positive η. It is then sufficient to show that $|\log Z(\beta, F) - \Phi(\beta, F)| \leq N\varepsilon$ whp for any $\varepsilon > 0$. Now, Eqs. (3.12) and (3.13) imply that

$$
\begin{aligned}
|\log Z(\beta, F) - \Phi(\beta, F)| &\leq \sum_{i=0}^{n-1} \left| \log \langle e^{-\Delta E(\underline{x})} \rangle_i + \Delta \langle E(\underline{x}) \rangle_{\mathrm{BP},i} \right| \\
&\leq \sum_{i=0}^{n-1} \left| \log \langle e^{-\Delta E(\underline{x})} \rangle_i + \Delta \langle E(\underline{x}) \rangle_i \right| \\
&\quad + \sum_{i=0}^{n-1} \Delta \left| \langle E(\underline{x}) \rangle_i - \langle E(\underline{x}) \rangle_{\mathrm{BP},i} \right| .
\end{aligned}
\tag{4.31}
$$

Consider the first term in (4.31): for any non-negative random variable X, $\log \langle e^{-X} \rangle \leq \langle e^{-X} \rangle - 1 \leq \langle 1 - X + X^2 \rangle - 1 \leq -\langle X \rangle + \langle X^2 \rangle$. As a consequence, we obtain

$$
\begin{aligned}
\sum_{i=0}^{n-1} \left| \log \langle e^{-\Delta E(\underline{x})} \rangle_i + \Delta \langle E(\underline{x}) \rangle_i \right| &\leq \sum_{i=0}^{n-1} \Delta^2 \langle E(\underline{x})^2 \rangle_i \\
&\leq \beta \Delta \sup_i \langle E(\underline{x})^2 \rangle_i \leq N^{2\delta} \alpha^2,
\end{aligned}
$$

where we used $\beta \leq N^\delta$, $\Delta = \beta/N^2 \leq N^{\delta-2}$ and $0 \leq E(\underline{x}) \leq N\alpha$. If we choose $\delta < 1/2$, this contribution is smaller than $N\varepsilon/2$ for all N large enough.

Now consider the second term in Eq. (4.31): the bound (3.30) holds for any β in the bounded interval $[0, N^\delta]$. Further, the left hand side is uniformly bounded (in terms of N) and continuous in β. Hence, there exists a C so that the bound (3.30) holds uniformly for $\beta \in [0, N^\delta]$. This will implies

$$
\begin{aligned}
\sum_{i=0}^{n-1} \Delta \, \mathbb{E} \left| \langle E(\underline{x}) \rangle_i - \langle E(\underline{x}) \rangle_{\mathrm{BP},i} \right| &\leq \beta C N^\xi \\
&\leq C N^{\delta+\xi}. \tag{4.32}
\end{aligned}
$$

Choosing $\delta \in (0, 1 - \xi)$, Markov inequality implies that the second term is also bounded above by $N\varepsilon/2$ whp. This completes the proof of Theorem 1. $\qquad\square$

4.2 Proofs of Theorems 2, 3, and 4. We only provide sketch of proofs for Theorems 2, 3 and 4.

Proof sketch for Theorem 2. By using the definition $\kappa(\alpha_*) = 1$ (with $\kappa(\alpha)$ being defined as in Eq. (2.3)), it is easy to show that $\alpha_*(k) = 2k^{-1} \log k \{1 + O(\log \log k / \log k)\}$. To complete the proof, we need a (asymptotically in k) matching upper bound. In order to obtain such an upper bound, we consider the case $\beta = \infty$, i.e. only satisfying assignments have positive weight. Consider a tree formula which is distributed as $\mathsf{T}_*(r)$. Let P_r be the probability that there exists two boundary conditions $\underline{x}_r^{(0)}$, $\underline{x}_r^{(1)}$, such that the root takes values, respectively, 0 or 1 in all the satisfying assignments with the respective boundary conditions. Clearly for the Gibbs measure to be unique (or have correlation decay) in the sense of Definition 1 (but also in the weaker sense correspondint to the threshold $\alpha_u'(k)$), it must be that $P_r \to 0$ as $r \to \infty$. Hence, if we establish that for $\alpha > 2k^{-1} \log k \{1 + O(\log \log k / \log k)\}$, there exists such boundary conditions with positive probability, then the proof will be complete. Next, we do that.

For this, consider a tree from $\mathsf{T}_*(r)$ with the root having degree 1. Given such a tree, let ρ_r be the probability that there exists a boundary condition $\underline{x}_r$, such that the root variable is the only variable that satisfies the only clause in which it belongs (recall that the root variable has degree 1) for all possible satisfying assignments with the given boundary condition. If $P_r \to 0$, then $\rho_r \to 0$. To prove this claim, assume by contraddiction that ρ_r remains bounded away from zero (say $\rho_r \geq \underline{\rho} > 0$) and consider an tree from $\mathsf{T}_*(r)$ (without conditioning). With finite probability the root belongs to two clauses in which it appears, respectively, directed and negated. With probability at least $\underline{\rho}^2 > 0$, for each of the corresponding subtrees there exists a boundary condition that fixes the root variable to be (respectively) directed or negated. By extending arbitrarily this boundary conditions to the full tree, we obtain the desired $\underline{x}_r^{(1)}$, $\underline{x}_r^{(0)}$.

It turns out that ρ_r is determined recursively as follows: $\rho_0 = 1$ and $\rho_{r+1} = \{1 - \exp(-k\alpha\rho_r/2)\}^{k-1}$. Recursively, $\rho_r \to 0$ as $r \to \infty$ only if $\alpha < \alpha^*(k)$, where $\alpha^*(k)$ for the above recursion (with little bit of algebra) evaluates to $\alpha^*(k) = 2k^{-1} \log k \{1 + O(\log \log k / \log k)\}$. This completes the proof sketch of Theorem 2.

Proof sketch for Theorem 3. First notice that, if F and F' differ in a single clause, then $|\log Z(\beta, F) - \log Z(\beta, F')| \leq 2\beta$. Hence, by application of Azuma-Hoeffding's inequality, it follows that $|\log Z - \mathbb{E} \log Z| \leq N\delta$ with probability at least $1 - e^{-NC_\beta \delta^2}$, for some $C_\beta > 0$ for any $\beta \in [0, \infty)$. Given this, to obtain the almost

sure convergence as in (2.8), it is sufficient to prove that $\lim_{N\to\infty} N^{-1}\mathbb{E}\,\Phi(\beta,F) = \phi(\beta)$, in light of Theorem 1 and Borel-Cantelli's Lemma.

To do so, first we need to establish that

$$\lim_{N\to\infty}\frac{1}{N}\mathbb{E}\langle E(\underline{x})\rangle_{\mathrm{BP},\beta} = \alpha\mathbb{E}g(h_1,\ldots,h_k)\,,\qquad(4.33)$$

where g is defined as in Eq. (3.27); the random variables $h_1,\ldots,h_k$ are i.i.d. with distribution ν^* that is a fixed point of the operator S as defined in the statement of Theorem 3. We claimed that the fixed point is unique for S. To justify this claim, first note that the image of S is contained in the space of distributions supported on $[0,\beta/2]$, call it $\mathcal{D}_\beta$, which is a compact space with respect to the weak topology. Being continuous on $\mathcal{D}_\beta$, S admits at least one fixed point in it. Moreover, the contraction condition implied by the correlation decay (proved as a part of Theorem 2) implies the attractiveness as well as the uniqueness of the fixed point of S.

Once we establish existence of the unique fixed point, the (4.33) follows from Lemma 3.2 and correlation decay established in Theorem 2. Now, by integrating Eq. (4.33) over β and observing that $\beta_{i+1}-\beta_i = \beta/N^2$ (hence the discretization error is negligible at scale $1/N$) one gets

$$\lim_{N\to\infty} N^{-1}\mathbb{E}\,\Phi(\beta,F) = \log 2 - \alpha\int_0^\beta \mathbb{E}_{\beta'}g(h_1,\ldots,h_k)\,\mathrm{d}\beta'\,,$$

where a subscript has been added in $\mathbb{E}_{\beta'}$ to stress that the fixed point distribution has to be taken at inverse temperature β'. The proof of Theorem 3 is completed by showing that the integral on the right hand side of the last equation is given by $\phi(\beta)$ as in Eq. (2.9). In fact, by taking the derivative of this expression wrt β, one gets a contribution coming from the explicit β dependence, which evaluates to $-\alpha\mathbb{E}g(h_1,\ldots,h_k)$, and one from the β dependence of the fixed poit distribution, that can be shown to vanish.

Proof Sketch of Theorem 4. For the ease of notation, let $Z(\beta) \equiv Z_N(\beta,F)$, $\Xi(\zeta) \equiv \Xi(\zeta,F)$ and $U(\beta) \equiv \langle E(\underline{x})\rangle_{\beta,F}$. Because of Theorem 1, it is sufficient to prove that $|\log\Xi(N\varepsilon)-\log Z(\beta)| \le N\varepsilon^a$ whp. This follows from two inequalities.

First inequality. For any $\zeta \ge 0$,

$$Z(\beta) = \sum_{\underline{x}:E(\underline{x})\ge\zeta} e^{-\beta E(\underline{x})} + \sum_{\underline{x}:E(\underline{x})<\zeta} e^{-\beta E(\underline{x})}$$
$$\ge e^{-\beta\zeta}\Xi(\zeta)\,.\qquad(4.34)$$

Second inequality. For any $\zeta \ge 0$ and using the first equality in (4.34), we obtain

$$Z(\beta) \le \sum_{\underline{x}:E(\underline{x})\ge\zeta} e^{-\beta E(\underline{x})} + \Xi(\zeta).$$

Equivalently, $Z(\beta)\mu(E(\underline{x}) < \zeta) \le \Xi(\zeta)$. Now, take $\zeta = 2U(\beta)$ then, we get using Markov's inequality

$$\mu\{E(\underline{x}) < 2U(\beta)\} \ge 1 - \frac{U(\beta)}{2U(\beta)} = \frac{1}{2}.\quad(4.35)$$

From (4.34) and (4.35), we obtain

$$\log Z(\beta) - \log 2 \le \log\Xi(2U(\beta))$$
$$\le \log Z(\beta) + 2\beta U(\beta).\quad(4.36)$$

The next step consists in controlling $U(\beta)$ at large β. Arguing analogously to the proof of Theorem 1 one can show that there exist constants C_1, C_2, C_3, $a > 0$ such that, for any $\beta \in [0,\infty]$, $NC_1e^{-2\beta} \le U(\beta) \le NC_2e^{-b\beta} + C_3N^\delta$ whp.

Fix β_1 in such a way that $2C_1e^{-2\beta_1} = \varepsilon$. Then $2U(\beta_1) \ge N\varepsilon$ whp. By the upper bound in Eq. (4.36) and monotonicit of $\Xi(\zeta)$, we get

$$\log\Xi(N\varepsilon) \le \log Z(\beta_1) + 2\beta_1 U(\beta_1)$$
$$\le \log Z(\beta_1) + 2\beta_1 NC_2e^{-b\beta_1} + 2\beta_1 C_3N^\delta\,.$$

Using the definition of β_1, which gives $\beta_1 = \frac{1}{2}\log\frac{2C_1}{\varepsilon}$, we get that there exists $C,a > 0$ such that

$$\log\Xi(N\varepsilon) \le \log Z(\beta_1) + NC\varepsilon^a\,.\qquad(4.37)$$

with high probability.

The lower bound on $\log\Xi(N\varepsilon)$ is proved analogously by taking β_2 such that $2C_2e^{-b\beta}+2C_3N^{-1+\delta} = \varepsilon$ thus getting $\log\Xi(N\varepsilon) \ge \log Z(\beta_2) - NC\varepsilon^a$ whp. One concludes by bounding the difference of the two partition functions: $|\log Z(\beta_2) - \log Z(\beta_1)| \le U(\beta_2)|\beta_1 - \beta_2| \le NC\varepsilon^a$ whp. $\square$

5 Discussion and Future Work

We presented a novel deterministic algorithm for approximately counting good truth assignments of random k-SAT formula with high probability. The algorithm is built upon the well-known Belief Propagation heuristic and an interpolation method for the log-partition function. In the process of establishing the correctness of the algorithm, we obtained the threshold for uniqueness of Gibbs distribution for random k-SAT formula as $2k^{-1}\log k(1 + o_k(1))$. This result if of interest in its own right.

We believe that our result can be extended to a reasonable class of non-random k-SAT formulas. We also believe that the approximation guarantees of Theorem 1 should hold for any $\beta \in [0,\infty]$.

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